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BENDING AND SHEAR STRESSES DEVELOPED BY THE INSTANTANEOUS  
ARREST OF THE ROOT OF A MOVING CANTILEVER BEAM

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and John C. Houbolt

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## NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

## ADVANCE RESTRICTED REPORT

BENDING AND SHEAR STRESSES DEVELOPED BY THE INSTANTANEOUS  
ARREST OF THE ROOT OF A MOVING CANTILEVER BEAMBy Elbridge Z. Stowell, Edward B. Schwartz  
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## SUMMARY

A theoretical and experimental investigation has been made of the behavior of a cantilever beam in transverse motion when its root is suddenly brought to rest. Equations are given for determining the stresses, the deflections, and the accelerations that arise in the beam as a result of the impact. The theoretical equations, which have been confirmed experimentally, reveal that, at a given percentage of the distance from root to tip, the bending stresses for a particular mode are independent of the length of the beam whereas the shear stresses vary inversely with the length.

## INTRODUCTION

When an airplane lands, the vertical component of the velocity is rapidly reduced to zero. In the absence of a thorough analysis of the stresses that arise from such shocks, it is customary for engineers to assume that the landing loads are static and independent of the elastic properties of the structure. As an initial step in the study of elastic structures under shock loads, an investigation has been made to determine the effect on a simple structure of the sudden arrest of its motion and the effect of the geometry of the structure on the stresses that result. The particular case treated in this report covers the basic problem of the instantaneous arrest of the root of a moving cantilever beam. The solution of this problem gives the energy consumed in exciting the different modes of vibration and the stresses, deflections, and accelerations that result throughout the beam.

This investigation is based on the usual engineering beam theory in which the deflections are considered to be the result of bending alone and shear deflections are neglected. The theory, as applied to ordinary beams, gives reasonably good results as long as the distance between inflection

points is greater than a few times the depth of the beam. When this theory for beam action is used in vibration problems, such as the problem in the present paper, the results are satisfactory for those modes of vibration for which the nodes are not too close together. This report summarizes the results of a theoretical solution, given in the appendix, and presents an experimental verification of these results.

### SYMBOLS

E	modulus of elasticity
$\gamma$	weight density of material
$\lambda$	coefficient of equivalent viscous damping of material
c	velocity of sound in material $(\sqrt{\frac{Eg}{\gamma}})$
g	acceleration of gravity
L	length of beam
I	moment of inertia of cross section of beam about neutral axis
A	cross-sectional area of beam
$\rho$	radius of gyration of cross section of beam $(\sqrt{\frac{I}{A}})$
x	coordinate along beam measured from root
y	distance from neutral axis of beam to any fiber
t	time, zero at impact
p	operator $\left(\frac{\partial}{\partial t}\right)$
n	integers 1, 2, 3, etc. designating a particular mode of vibration
$\theta_n$	nth positive root of $1 + \cos \theta \cosh \theta = 0$
$\omega_n$	undamped natural angular frequency of nth mode, radians per second $\left(\rho c \frac{\theta_n^2}{L^2}\right)$

$\omega_n'$  damped natural angular frequency of nth mode,  
radians per second  $\left( \omega_n \sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}} \right)$

~~at natural~~ ~~does not~~ ~~a beam~~ ~~balance~~ ~~according to~~ ~~above~~ ~~and~~ ~~the~~ ~~frequency~~ ~~is defined~~  
When  $\frac{\lambda^2 \omega_n^2}{4E^2} > 1$ , the "frequency" is defined  
by  $\omega_n' = \omega_n \sqrt{\frac{\lambda^2 \omega_n^2}{4E^2} - 1}$

$v$  velocity of beam prior to impact

$w(x, t)$  deflection of beam at station  $x$  and time  $t$

$w_n(x, t)$  deflection of beam at station  $x$  and time  $t$   
for nth mode of vibration

$a(x, t)$  acceleration of beam at station  $x$  and time  $t$

$a_n(x, t)$  acceleration of beam at station  $x$  and time  $t$   
for nth mode of vibration

$\sigma(x, y, t)$  bending stress in beam at station  $x$ , distance  
from neutral axis  $y$ , and time  $t$

$\sigma_n(x, y, t)$  bending stress in beam at station  $x$ , distance  
from neutral axis  $y$ , and time  $t$  for  
nth mode of vibration

$\bar{\tau}(x, t)$  average shear stress over cross section of beam  
at station  $x$  and time  $t$

$\bar{\tau}_n(x, t)$  average shear stress over cross section of beam  
at station  $x$  and time  $t$  for nth mode of  
vibration

$A_n$  bending-stress coefficient

$B_n$  shear-stress coefficient

$C_n$  deflection coefficient

## RESULTS AND CONCLUSIONS

## Theoretical

When a cantilever beam under uniform translation in a direction perpendicular to its length has its root instantaneously brought to rest, there is excited a theoretically infinite number of modes of vibration. With each successive mode, damping has an increasing influence upon the frequencies and amplitudes of vibration and, for sufficiently high modes, even changes the type of motion from oscillatory to nonoscillatory motion. In the lower modes, however, damping has little effect, and only terms of the first order in damping need to be included in the equations. Only the equations applicable to the lower modes, which alone are of importance in any practical case, are presented in this section of the paper. For a more complete treatment of damping, see the appendix.

The angular frequencies ( $2\pi$  times the frequencies in cps) are given by the equation

$$\omega_n = \rho c \frac{\theta_n^2}{L^2} \quad (1)$$

where  $\theta_n$  has the following values for successive modes of vibration:

$$\begin{aligned} \theta_1 &= 1.875104 & \theta_5 &\approx 14.137168 \\ \theta_2 &= 4.694098 & \theta_6 &\approx 17.278759 \\ \theta_3 &= 7.854757 & \theta_n &\approx \frac{1}{2} (2n-1)\pi, \quad n > 6 \\ \theta_4 &= 10.995541 \end{aligned}$$

The energy that the beam possesses before impact is consumed in exciting the various modes of vibration and is distributed among the modes as follows:

Mode, n	Percentage of energy
1	61.3
2	18.8
3	7.4
4	3.2
5	1.9
6	1.3
7 to $\infty$	6.1

This distribution of energy among the different modes of vibration is presented graphically in figure 1.

All stresses, deflections, and accelerations are damped sinusoidal functions of time and vary along the length of the beam. The bending stress  $\sigma_n(x,y,t)$  and the average shear stress  $\bar{\tau}_n(x,t)$ , associated with the nth mode of vibration, are given by the equations

$$\sigma_n(x,y,t) = A_n \frac{v}{c} \frac{y}{\rho} E e^{-\frac{\lambda \omega_n^2}{2E} t} \sin \omega_n t \quad (2)$$

$$\bar{\tau}_n(x,t) = B_n \frac{v}{c} \frac{\rho}{L} E e^{-\frac{\lambda \omega_n^2}{2E} t} \sin \omega_n t \quad (3)$$

The variation of the dimensionless coefficients  $A_n$  and  $B_n$  with  $x/L$  is given for  $n = 1, 2$ , and  $3$  in figures 2 and 3. The highest values of  $A_n$  and  $B_n$ , and hence the highest stresses, occur at the root of the beam. These values, for the first six modes, are

Mode, n	$A_n$ at root	$B_n$ at root
1	1.566	2.146
2	.868	4.149
3	.509	3.994
4	.364	4.00
5	.283	4.00
6	.231	4.00

The foregoing values of  $A_n$  and  $B_n$  at the root are presented graphically in figure 4.

The maximum values with respect to time of  $\sigma_n(x,y,t)$  and  $\bar{\tau}_n(x,t)$  associated with the nth mode of vibration, when the effects of damping are neglected, are

$$\sigma_n(x, y) = A_n \frac{v}{c} \frac{y}{\rho} E \quad (4)$$

$$\bar{\tau}_n(x) = B_n \frac{v}{c} \frac{\rho}{L} E \quad (5)$$

The deflections  $w_n(x, t)$  for the  $n$ th mode of vibration are given by the equation

$$w_n(x, t) = C_n \frac{v}{c} \frac{L^2}{\rho} e^{-\frac{\lambda \omega_n^2}{2E} t} \sin \omega_n t \quad (6)$$

The accelerations  $a_n(x, t)$  for the  $n$ th mode, when damping is sufficiently small, are given by

$$a_n(x, t) = -\omega_n^2 w_n(x, t) \quad (7)$$

The variation of the dimensionless coefficient  $C_n$  with  $x/L$  is given for  $n = 1, 2$ , and 3 in figure 5.

The equations (4) to (7) for stress, deflection, and acceleration give the values associated with the  $n$ th mode of vibration. Since all modes of vibration occur simultaneously, the net results are the superposition of the effects of all modes. This superposition gives the following equations:

For bending stress,

$$\sigma(x, y, t) = \frac{v}{c} \frac{y}{\rho} E \left( A_1 e^{-\frac{\lambda \omega_1^2}{2E} t} \sin \omega_1 t + A_2 e^{-\frac{\lambda \omega_2^2}{2E} t} \sin \omega_2 t + \dots \right) \quad (8)$$

For average shear stress,

$$\bar{\tau}(x, t) = \frac{v}{c} \frac{\rho}{L} E \left( B_1 e^{-\frac{\lambda \omega_1^2}{2E} t} \sin \omega_1 t + B_2 e^{-\frac{\lambda \omega_2^2}{2E} t} \sin \omega_2 t + \dots \right) \quad (9)$$

For deflection

$$w(x,t) = \frac{v}{c} \frac{L^2}{\rho} \left( C_1 e^{-\frac{\lambda \omega_1^2}{2E} t} \sin \omega_1 t + C_2 e^{-\frac{\lambda \omega_2^2}{2E} t} \sin \omega_2 t + \dots \right) \quad (10)$$

For acceleration, when damping is sufficiently small,

$$a(x,t) = \frac{v}{c} \frac{L^2}{\rho} \left( C_1 \omega_1^2 e^{-\frac{\lambda \omega_1^2}{2E} t} \sin \omega_1 t + C_2 \omega_2^2 e^{-\frac{\lambda \omega_2^2}{2E} t} \sin \omega_2 t + \dots \right) \quad (11)$$

The equation for bending stress (equation (4)) reveals that, at a given percentage of the distance from root to tip, the bending stress for a particular mode is independent of the length of the beam and depends only on the velocity before impact. The equation for shear stress (equation (5)) reveals that the shear stresses at any station vary inversely with the length of the beam. These results are contrary to those that might be expected on the basis of experience with the static behavior of structures. For this reason an experimental investigation was made.

### Experimental

A circular steel tube of 1-inch outside diameter and 0.028-inch wall thickness was mounted symmetrically on the end of a pendulum to form a pair of cantilever beams. (See fig. 6.) The pendulum was permitted to start its swing from a predetermined position and was suddenly brought to rest at the bottom of its swing against an electromagnet used to prevent rebound. The effect of length was studied by reducing the length of the tube in successive tests. The bending and shear strains were measured by electrical strain gages that were mounted on the tube as shown in figure 7. Each pair of gages was incorporated into a Wheatstone bridge circuit as shown diagrammatically in figure 8. The outputs of the bridge

systems were fed through a strain-gage amplifier into a multichannel oscillograph that recorded the strains on moving photographic paper. The amplitude of the components of strain due to the modes of higher frequency was reduced, however, because of the response characteristics of the oscillograph. The frequency-response curve for the oscillograph used is given in figure 9.

Typical records for tubes of two lengths are shown in figure 10. Inspection of the record for the cantilever beam  $26\frac{3}{4}$  inches long shows the superposition of the second and third modes upon the first mode. The record shows that, in the case of the bending strain, the contribution of the second mode is small; whereas, in the case of the shear strain, the contribution of the second mode is large. This observation confirms qualitatively the theoretical results shown in figure 4. The same effect is not shown, however, in the record for the cantilever beam  $11\frac{3}{4}$  inches long because of the combined action of damping and reduced response of the oscillograph to the higher frequencies associated with this short length of tube.

The bending stresses computed by use of equation (8), in which only the first three modes are used, are given by the solid-line curve of figure 11 for the cantilever beam  $26\frac{3}{4}$  inches long. Comparison of this curve with the record obtained during the first  $\frac{1}{2}$  cycle of the first mode (see fig. 10) shows good agreement as regards the wave shape.

Because of the damping present in the tube and the response characteristics of the oscillograph, the only component of vibration that could be satisfactorily recorded for all lengths of cantilever tube was the fundamental or first mode. The quantitative results of the tests consequently were based upon this mode of vibration. This procedure is sound because the effects of the various harmonics are independent of one another. In the analysis of the results, the data had to be corrected for the influence of the magnet.

The observed frequencies are compared with the frequencies computed from equation (1) for the first mode in the following table:

Length (in.)	Frequency	
	Observed (cps)	Computed (cps)
46 $\frac{3}{4}$	17.5	17.5
36 $\frac{3}{4}$	27.9	28.2
26 $\frac{3}{4}$	52.1	53.2
16 $\frac{3}{4}$	131	137
11 $\frac{3}{4}$	272	277

The experimental values of extreme-fiber bending stresses and the shear stresses at the root, for the fundamental mode, are plotted in figure 12. In figure 12 are also shown the corresponding theoretical curves of equation (4) for bending and equation (5) for shear with  $n$  taken as 1. It is observed that the experimental points follow the trend of and lie close to the theoretical curves.

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$$(4A) \quad \sigma = \frac{\pi^2 E}{320 \cdot 5950} \cdot \frac{L}{354 \cdot 26} \cdot \frac{L}{2} \cdot \frac{\pi^2 E}{34}$$

where  $L$  is the length of the beam in inches,  $E$  is the modulus of elasticity in psi, and  $\sigma$  is the bending stress in psi.

$$\text{and } \frac{L}{34} = n \text{ and } \frac{L}{2} = m$$

$$(5A) \quad \tau = \frac{\pi^2 E}{320 \cdot 5950} \cdot \frac{m}{n^2} \left( \frac{n}{2} + 1 \right)$$

## APPENDIX

## THEORETICAL DERIVATION

General analysis. - Consider a beam of uniform cross section in equilibrium. If a portion of the beam is suddenly disturbed, as by a shock, in a direction perpendicular to its length, the beam is set into damped bending oscillations. The equation of motion for these bending oscillations is given by the differential equation (reference 1)

$$E\rho^2 \frac{\partial^4 w}{\partial x^4} + \lambda \rho^2 \frac{\partial^5 w}{\partial x^4 \partial t} + \frac{\gamma}{g} \frac{\partial^2 w}{\partial t^2} = 0 \quad (A1)$$

The damping term  $\lambda \rho^2 \frac{\partial^5 w}{\partial x^4 \partial t}$  is derived on the

assumption that the longitudinal damping force per unit area at any point on the cross section of the beam is proportional to the rate of change of longitudinal strain at that point. (See reference 2.) This type of force is analogous to ordinary viscous drag, in which the tangential force per unit area is proportional to the rate of change of shear strain. With the use of the notation  $c^2 = \frac{Eg}{\gamma}$ , equation (A1) can be written

$$\frac{\partial^4 w}{\partial x^4} + \frac{\lambda}{E} \frac{\partial^5 w}{\partial x^4 \partial t} + \frac{1}{c^2 \rho^2} \frac{\partial^2 w}{\partial t^2} = 0 \quad (A2)$$

In accordance with the Heaviside operational methods (reference 3), equation (A2) may be reduced to an ordinary differential equation of the fourth order by writing  $p = \frac{\partial}{\partial t}$ ; thus,

$$\left(1 + \frac{\lambda}{E} p\right) \frac{d^4 w}{dx^4} + \frac{p^2}{c^2 \rho^2} w = 0 \quad (A3)$$

The general solution of equation (A3) is

$$w = P \cosh \theta \frac{x}{L} + Q \sinh \theta \frac{x}{L} + R \sin \theta \frac{x}{L} + S \cos \theta \frac{x}{L} \quad (A4)$$

where

$$\theta = L \sqrt{\frac{ip}{\rho c \sqrt{1 + p \frac{\lambda}{E}}}}$$

The coefficients P, Q, R, and S are to be determined from the boundary conditions. The case under consideration is that of a cantilever moving with uniform velocity  $v$  and having its base brought instantaneously to rest. The boundary conditions for this case are

$$\left( \frac{\partial w}{\partial t} \right)_{x=0} = p(w)_{x=0} = v - v1$$

$$\left( \frac{\partial w}{\partial x} \right)_{x=0} = \left( \frac{\partial^2 w}{\partial x^2} \right)_{x=L} = \left( \frac{\partial^3 w}{\partial x^3} \right)_{x=L} = 0$$

The velocity of the root as given by the first boundary condition is represented graphically in figure 13(a). The rules of the Heaviside calculus, however, have been devised for a disturbance, called the unit function<sup>1</sup>, shown in figure 13(b). By the principle of superposition, the velocity function shown in figure 13(a) may be considered as a superposition of those shown in figures 13(c) and 13(d). The velocity therefore consists of a constant velocity  $v$  (fig. 13(c)) added to the solution of the problem obtained by the Heaviside expansion theorem for the disturbance shown in figure 13(d). On the basis of this procedure, the first boundary condition may be written

$$\left( \frac{\partial w}{\partial t} \right)_{x=0} = p(w)_{x=0} = -v1$$

With the application of the boundary conditions to equation (A4), the operational form of the solution for the velocity (that induced by the disturbance) is found to be

$$\begin{aligned}
 p_w = & \frac{-vI}{2(1 + \cosh \theta \cos \theta)} \left[ (1 + \cos \theta \cosh \theta) \left( \cosh \theta \frac{x}{L} + \cos \theta \frac{x}{L} \right) \right. \\
 & + \sin \theta \sinh \theta \left( \cosh \theta \frac{x}{L} - \cos \theta \frac{x}{L} \right) \\
 & \left. + (\sinh \theta \cos \theta + \cosh \theta \sin \theta) \left( \sin \theta \frac{x}{L} - \sinh \theta \frac{x}{L} \right) \right] \quad (A5)
 \end{aligned}$$

Interpretation of this operational expression and addition of the constant velocity  $v$  gives for the total velocity

$$\frac{\partial w(x, t)}{\partial t} = v - vI + 2v \sum_{n=1}^{\infty} F\left(\theta_n \frac{x}{L}\right) e^{-\frac{\lambda \omega_n^2}{2E} t} \left( \cos \omega_n' t - \frac{\frac{\lambda \omega_n}{2E}}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} \sin \omega_n' t \right) \quad (A6)$$

where  $\omega_n$  is the  $n$ th positive root of  $1 + \cos \theta \cosh \theta = 0$

$\theta_n$  is the  $n$ th positive root of  $1 + \cos \theta \cosh \theta = 0$

$$\omega_n = \rho c \frac{\theta_n^2}{L^2} \quad \text{undamped natural angular frequency of } n\text{th mode, radians/sec}$$

$$\omega_n' = \omega_n \sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}} \quad \text{damped natural angular frequency of } n\text{th mode, radians/sec}$$

$$F\left(\theta_n \frac{x}{L}\right) = \frac{\sin \theta_n \sinh \theta_n \left(\cosh \theta_n \frac{x}{L} - \cos \theta_n \frac{x}{L}\right) - \left(\cosh \theta_n \sin \theta_n + \sinh \theta_n \cos \theta_n\right) \left(\sinh \theta_n \frac{x}{L} - \sin \theta_n \frac{x}{L}\right)}{\theta_n \left(\cosh \theta_n \sin \theta_n - \sinh \theta_n \cos \theta_n\right)}$$

Integration of equation (A6) with respect to the time with the condition  $(w)_{t=0} = 0$  gives for the deflection

$$\begin{aligned} w(x, t) &= 2v \sum_{n=1}^{\infty} \frac{F\left(\theta_n \frac{x}{L}\right)}{\omega_n} e^{-\frac{\lambda \omega_n^2}{2E} t} \sin \omega_n' t \\ &= \frac{v}{c} \frac{L^2}{\rho} \sum_{n=1}^{\infty} c_n \frac{1}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} e^{-\frac{\lambda \omega_n^2}{2E} t} \sin \omega_n' t \end{aligned} \quad (A7)$$

where

$$c_n = \frac{2F\left(\theta_n \frac{x}{L}\right)}{\theta_n^2}$$

The contribution of the  $n$ th mode to the deflection is

$$w_n(x, t) = \frac{v}{c} \frac{L^2}{\rho} c_n \frac{1}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} e^{-\frac{\lambda \omega_n^2}{2E} t} \sin \omega_n' t \quad (A8)$$

When  $\frac{\lambda\omega_n}{2E} > 1$ , equation (A8) may be put in the form

$$w_n(x, t) = \frac{v}{c} \frac{L^2}{\rho} C_n \frac{1}{\sqrt{\frac{\lambda^2\omega_n^2}{4E^2} - 1}} e^{-\frac{\lambda\omega_n^2}{2E}t} \sinh \omega_n' t \quad (A9)$$

where now

$$\omega_n' = \omega_n \sqrt{\frac{\lambda^2\omega_n^2}{4E^2} - 1}$$

The form indicated by equation (A8), where  $\frac{\lambda\omega_n}{2E} < 1$ , is characteristic of the lower modes and represents damped oscillatory motion. The form indicated by equation (A9), where  $\frac{\lambda\omega_n}{2E} > 1$  (damping greater than critical), is characteristic of the higher modes and represents subsidence motion.

From equation (A6) for velocity and equation (A7) for deflection, the complete behavior of the cantilever may be determined. The quantities of interest are the bending stresses, the shear stresses, and to some extent the accelerations. When damping is present, the equations representing the contribution of the nth mode to these quantities may be given in the two forms indicated by equations (A8) and (A9). In subsequent equations, however, only the form indicated by equation (A8) is given because it is characteristic of the modes that are of practical importance.

Bending stresses.- The bending stresses  $\sigma(x, y, t)$  at any fiber distance  $y$  from the neutral axis are

$$\sigma(x, y, t) = E y \frac{\partial^2 w}{\partial x^2}$$

$$= E \frac{v}{c} \frac{y}{p} \sum_{n=1}^{\infty} A_n \frac{1}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} e^{-\frac{\lambda \omega_n^2 t}{2E}} \sin \omega_n' t$$

where

$$A_n = \frac{\sin \theta_n \sinh \theta_n (\cosh \theta_n \frac{x}{L} + \cos \theta_n \frac{x}{L}) - (\cosh \theta_n \sin \theta_n + \sinh \theta_n \cos \theta_n) (\sinh \theta_n \frac{x}{L} + \sin \theta_n \frac{x}{L})}{\theta_n (\cosh \theta_n \sin \theta_n - \sinh \theta_n \cos \theta_n)}$$

The bending stress due to only the nth mode is

$$\sigma_n(x, y, t) = E \frac{v}{c} \frac{y}{p} A_n \frac{1}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} e^{-\frac{\lambda \omega_n^2 t}{2E}} \sin \omega_n' t$$

Shear stresses. - The average shear stress over the cross section  $\bar{\tau}(x, t)$  is

$$\bar{\tau}(x, t) = E \rho^2 \frac{\partial^3 w}{\partial x^3}$$

$$= E \frac{v}{c} \frac{\rho}{L} \sum_{n=1}^{\infty} B_n \frac{1}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} e^{-\frac{\lambda \omega_n^2}{2E} t} \sin \omega_n' t \mathbf{1}$$

where

$$B_n = 2 \frac{\sin \theta_n \sinh \theta_n \left( \sinh \theta_n \frac{x}{L} - \sin \theta_n \frac{x}{L} \right) - \left( \cosh \theta_n \sin \theta_n + \sinh \theta_n \cos \theta_n \right) \left( \cosh \theta_n \frac{x}{L} + \cos \theta_n \frac{x}{L} \right)}{\cosh \theta_n \sin \theta_n - \sinh \theta_n \cos \theta_n}$$

The average shear stress due to only the nth mode is

$$\bar{\tau}_n(x, t) = E \frac{v}{c} \frac{\rho}{L} B_n \frac{1}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} e^{-\frac{\lambda \omega_n^2}{2E} t} \sin \omega_n' t \mathbf{1}$$

Accelerations. - From equation (A6), with the aid of the relation

$$pF(t)\mathbf{1} = F(0)p\mathbf{1} + F'(t)\mathbf{1}$$

the acceleration anywhere on the beam is found to be

$$a(x, t) = \frac{\partial^2 w(x, t)}{\partial t^2} = \left[ 2 \sum_{n=1}^{\infty} F\left(\theta_n \frac{x}{L}\right) - 1 \right] vp1$$

$$- \frac{v}{c} \frac{L^2}{\rho} \sum_{n=1}^{\infty} c_n \frac{\omega_n^2 \left(1 - \frac{\lambda^2 \omega_n^2}{2E^2}\right)}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} e^{-\frac{\lambda \omega_n^2}{2E} t} \left( \sin \omega_n' t + \frac{\frac{\lambda \omega_n}{E} \sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}}{1 - \frac{\lambda^2 \omega_n^2}{2E^2}} \cos \omega_n' t \right) 1$$

With the aid of the orthogonal properties of the functions  $F\left(\theta_n \frac{x}{L}\right)$  it is possible to show that the quantity  $2 \sum_{n=1}^{\infty} F\left(\theta_n \frac{x}{L}\right) - 1$  reduces to zero when  $0 < \frac{x}{L} \leq 1$ .

At  $\frac{x}{L} = 0$ , the quantity  $2 \sum_{n=1}^{\infty} F\left(\theta_n \frac{x}{L}\right)$  equals zero, and only the

term  $-vp1$  remains. This term indicates that at  $t = 0$  an infinite acceleration of zero duration exists at the root.

The acceleration due to only the  $n$ th mode is

$$a_n(x, t) = -\frac{v}{c} \frac{L^2}{\rho} \omega_n^2 c_n \frac{1 - \frac{\lambda^2 \omega_n^2}{2E^2}}{\sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}} e^{-\frac{\lambda \omega_n^2}{2E} t} \left( \sin \omega_n' t + \frac{\frac{\lambda \omega_n}{E} \sqrt{1 - \frac{\lambda^2 \omega_n^2}{4E^2}}}{1 - \frac{\lambda^2 \omega_n^2}{2E^2}} \cos \omega_n' t \right) 1$$

Comparison with the expression for  $w_n(x, t)$  (equation (A8)) shows that the acceleration for each mode is out of phase with the deflection. When damping is sufficiently small, however, the relation between the acceleration and the deflection reduces to the well-known result for undamped vibration

$$a_n(x, t) = -\omega_n^2 w_n(x, t)$$

## REFERENCES

1. Den Hartog, J. P.: Mechanical Vibrations. Second ed., McGraw-Hill Book Co., Inc., 1940, p. 180.
2. Honda, Kotaro, and Konno, Seihei: On the Determination of the Coefficient of Normal Viscosity of Metals. Phil. Mag., ser. 6, vol. 42, no. 247, July 1921, pp. 115-123.
3. Carson, John R.: Electric Circuit Theory and the Operational Calculus. McGraw-Hill Book Co., Inc., 1926.

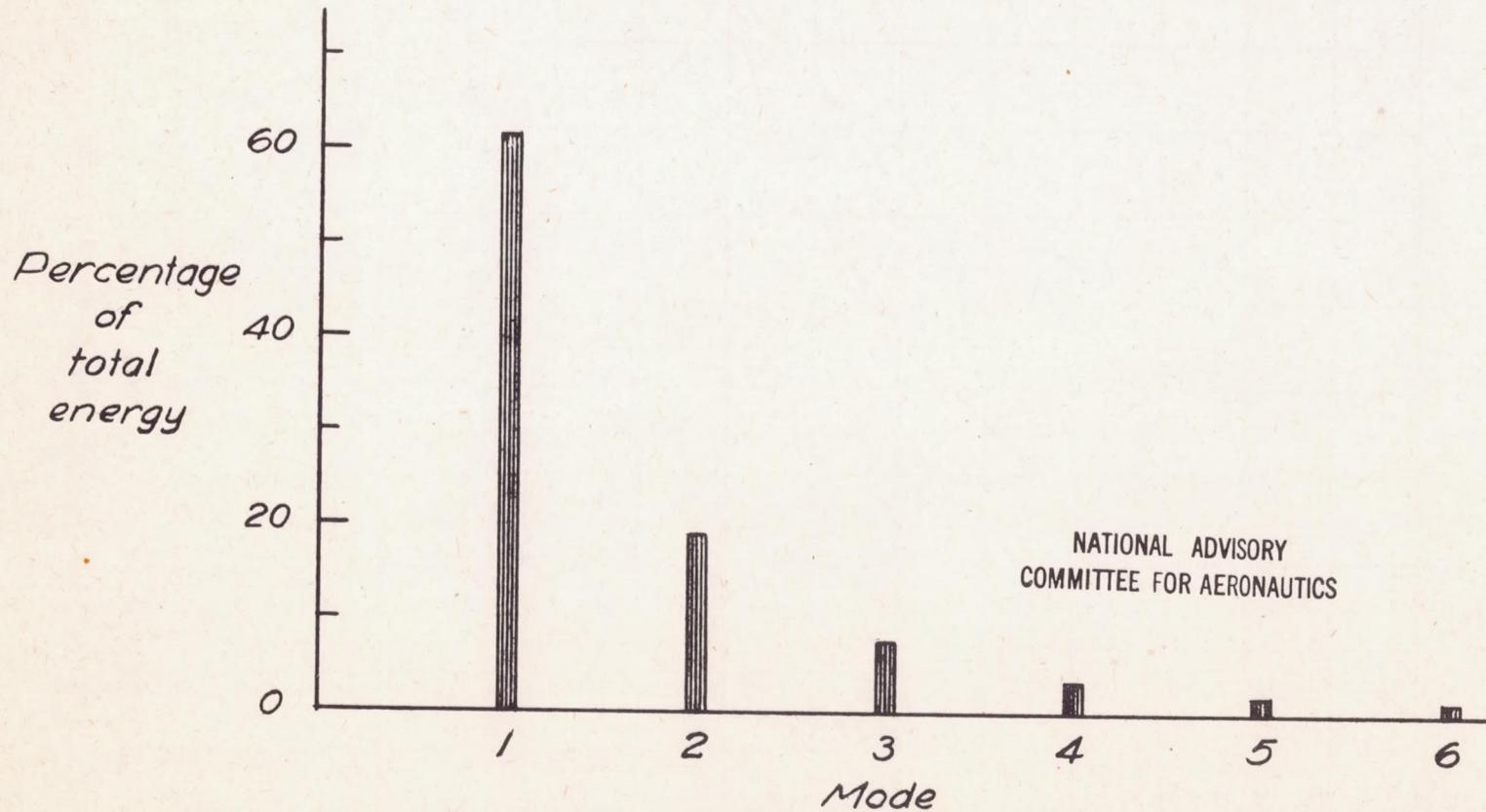


Figure 1.-Distribution of energy among the modes of vibration.

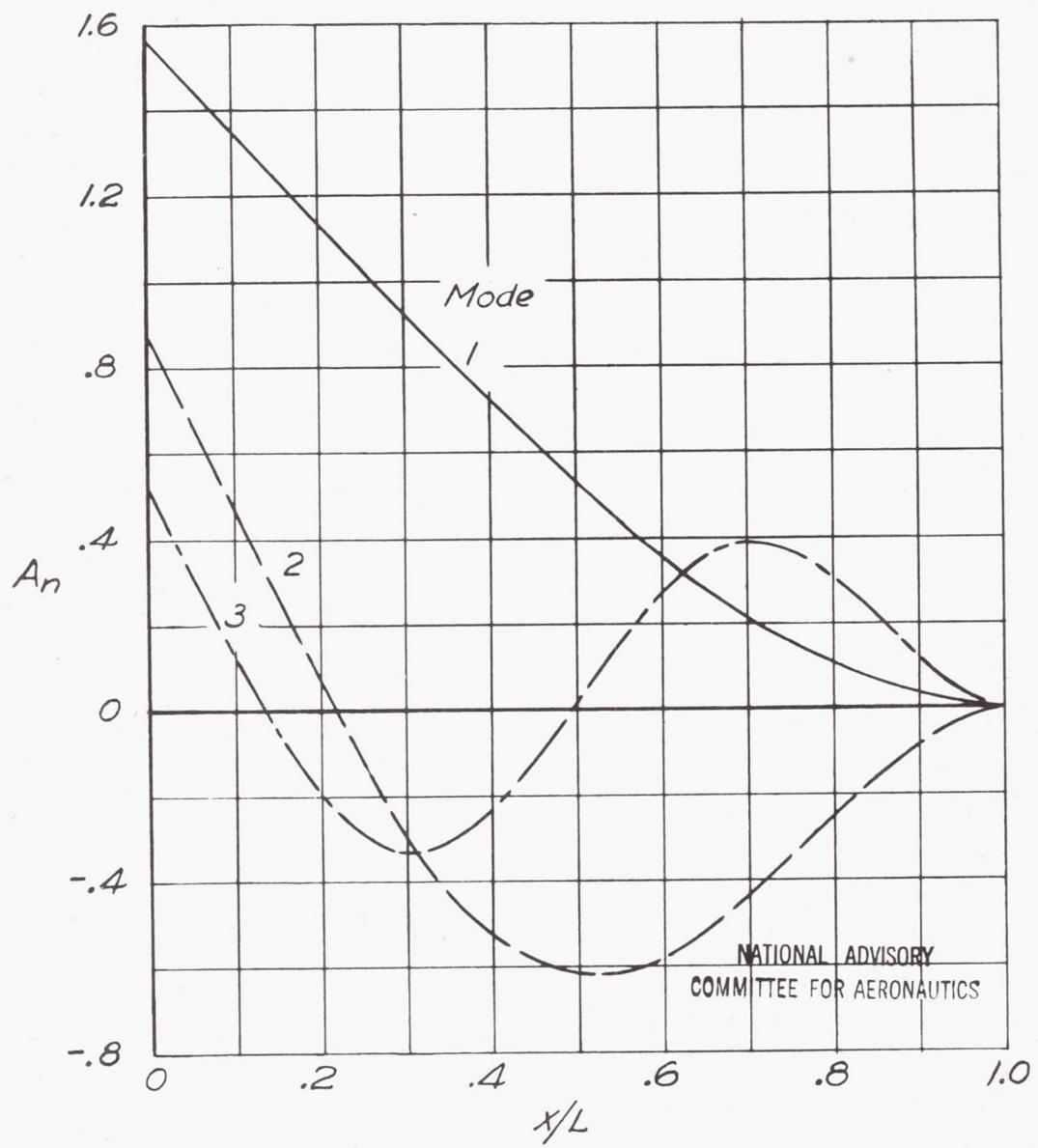


Figure 2.- Variation of bending-stress coefficient  $A_n$  with  $x/L$ .

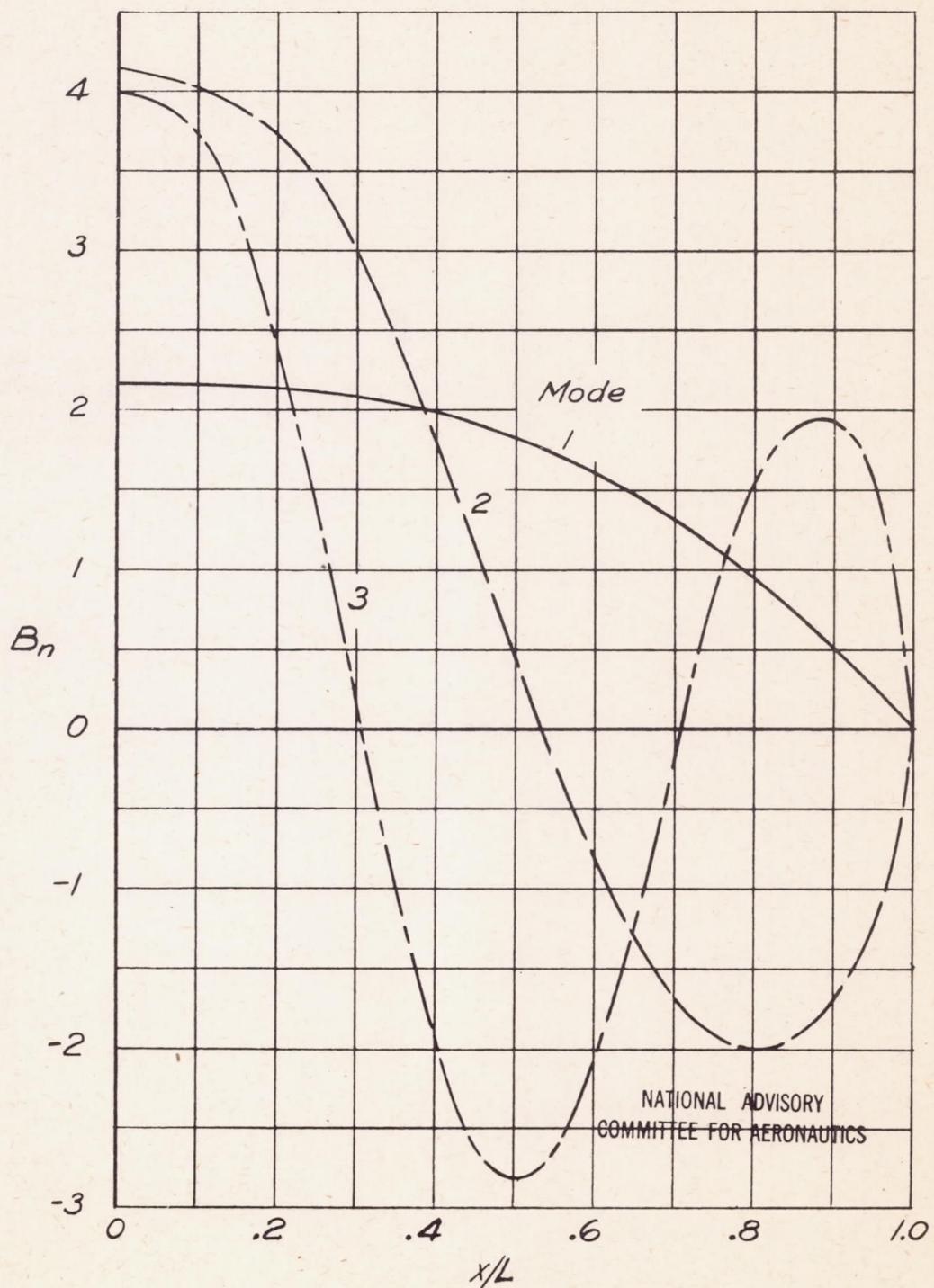
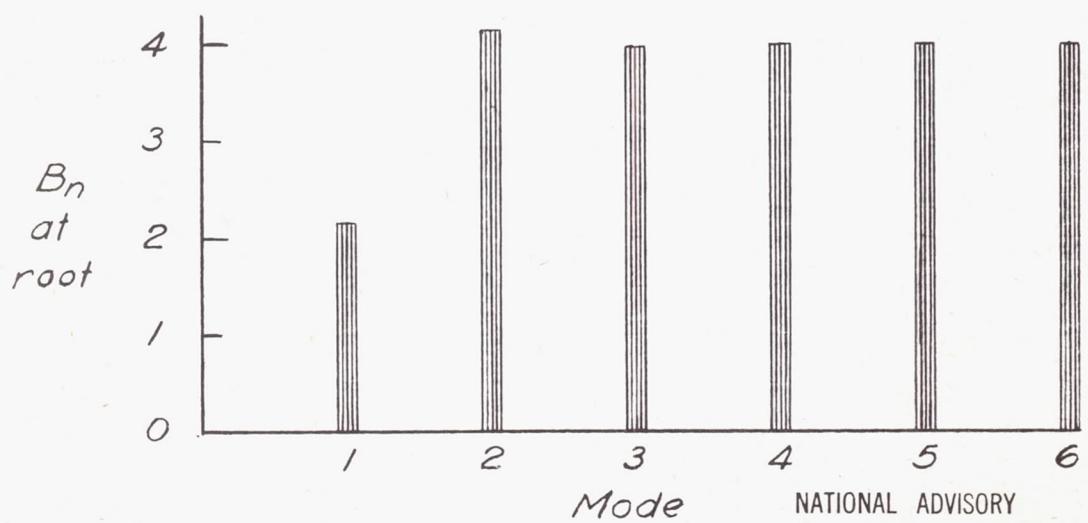
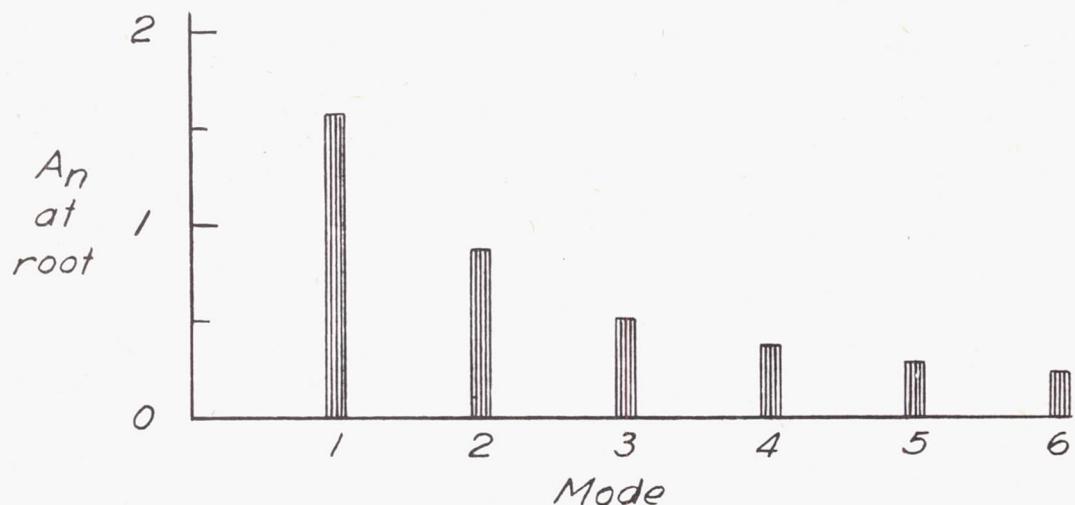


Figure 3.- Variation of shear-stress coefficient  $B_n$  with  $x/L$ .

Fig. 4

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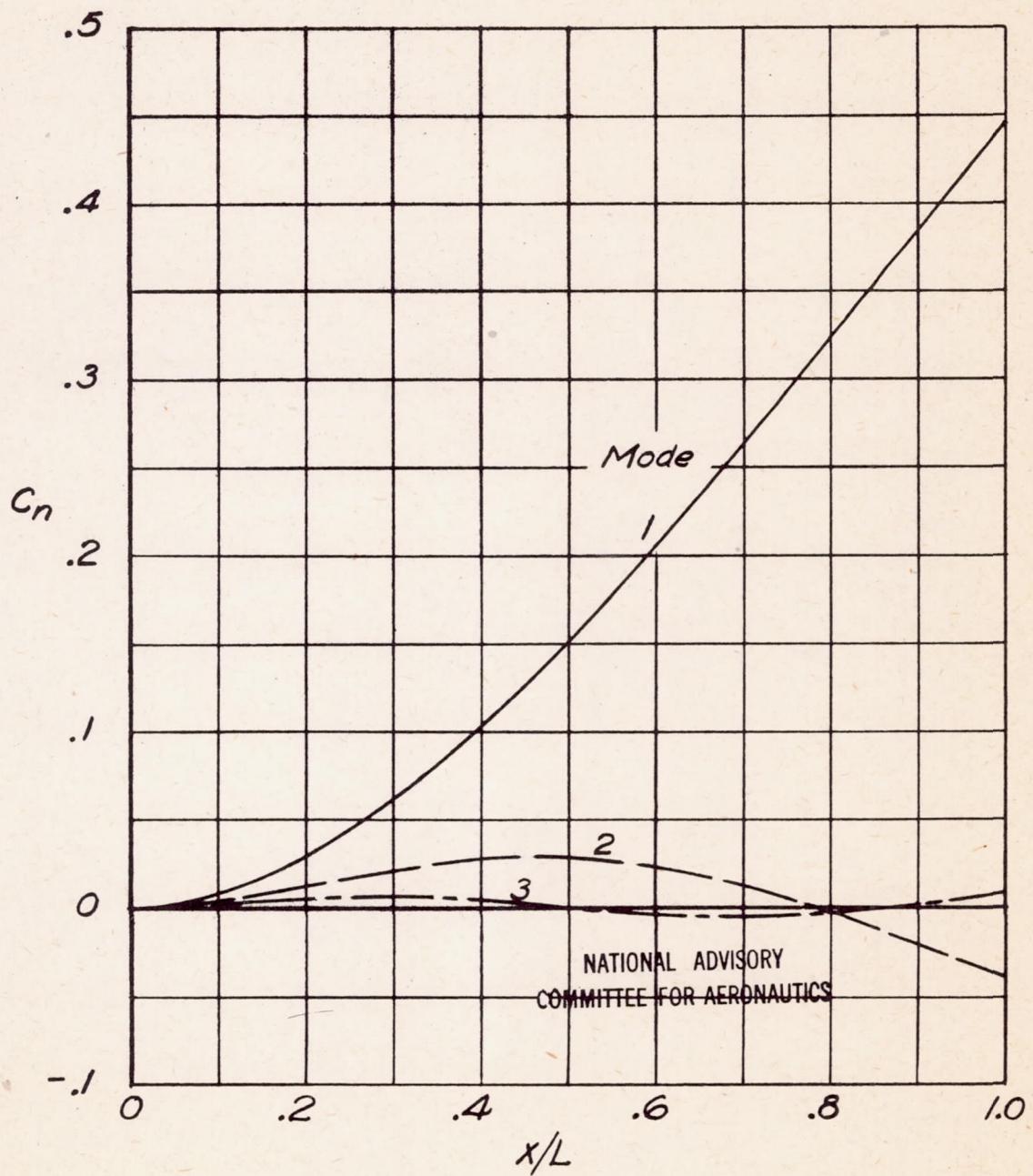


Figure 5.-Variation of deflection coefficient  $C_n$  with  $x/L$ .

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Fig. 6

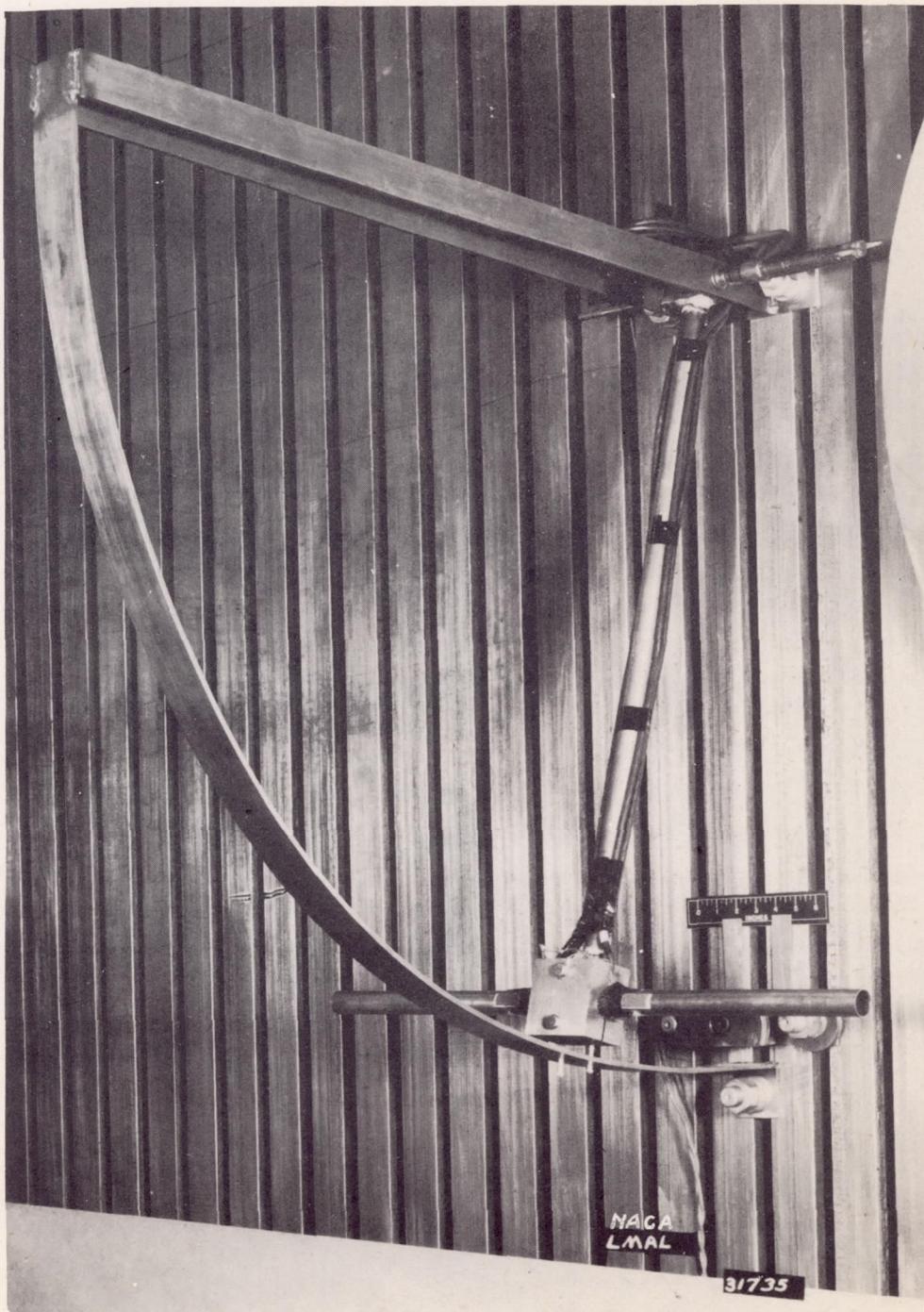


Figure 6.- Pendulum assembly used in impact test.

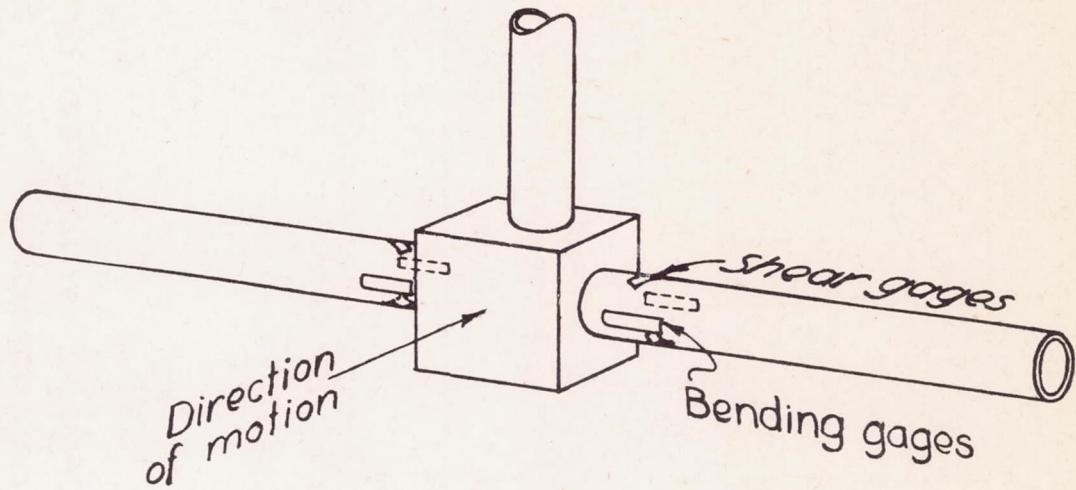


Figure 7.- Location of strain gages on tube.

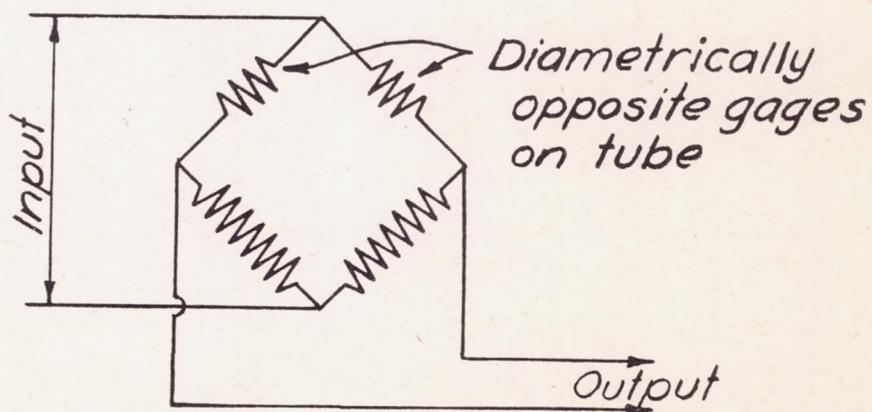
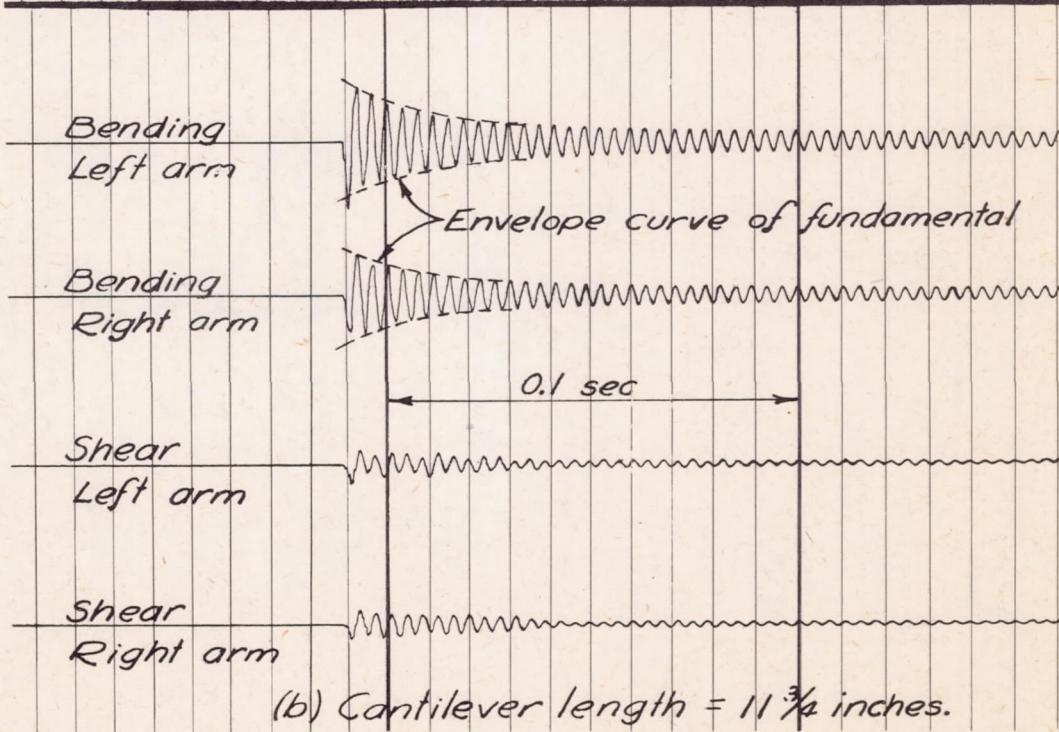
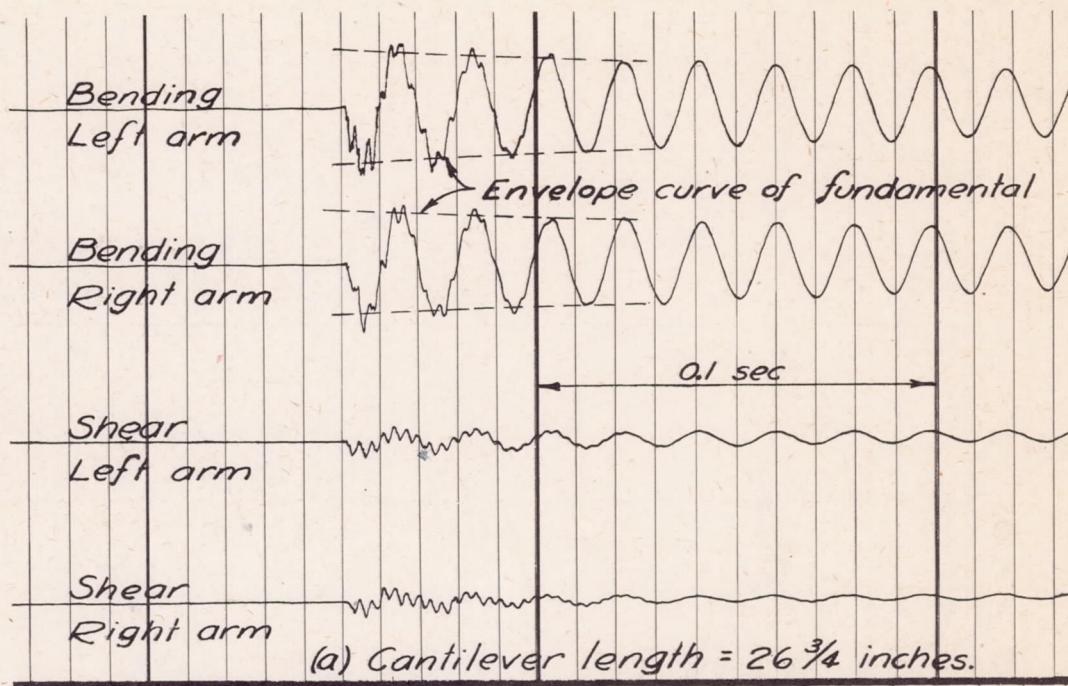


Figure 8.- Bridge circuit used in tests.

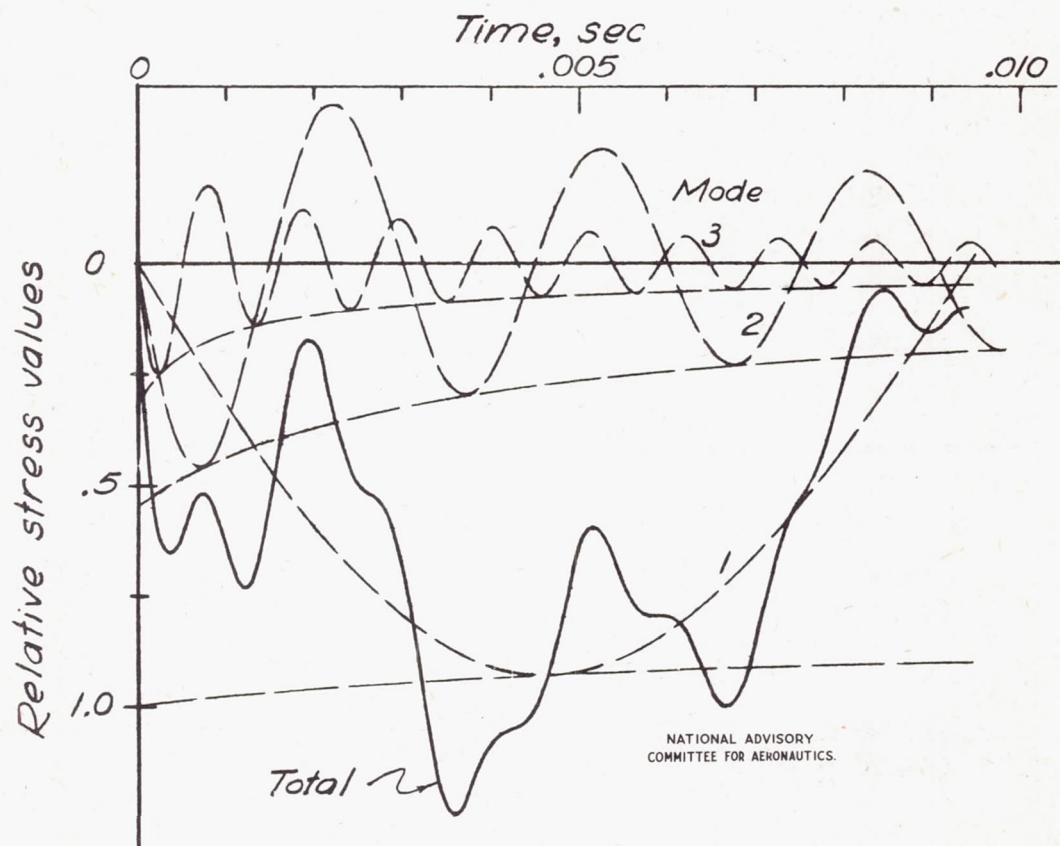


Figure 9.-Frequency response of strain-gage amplifier and Miller (2000 ~) oscillograph; 0.69 critical damping.



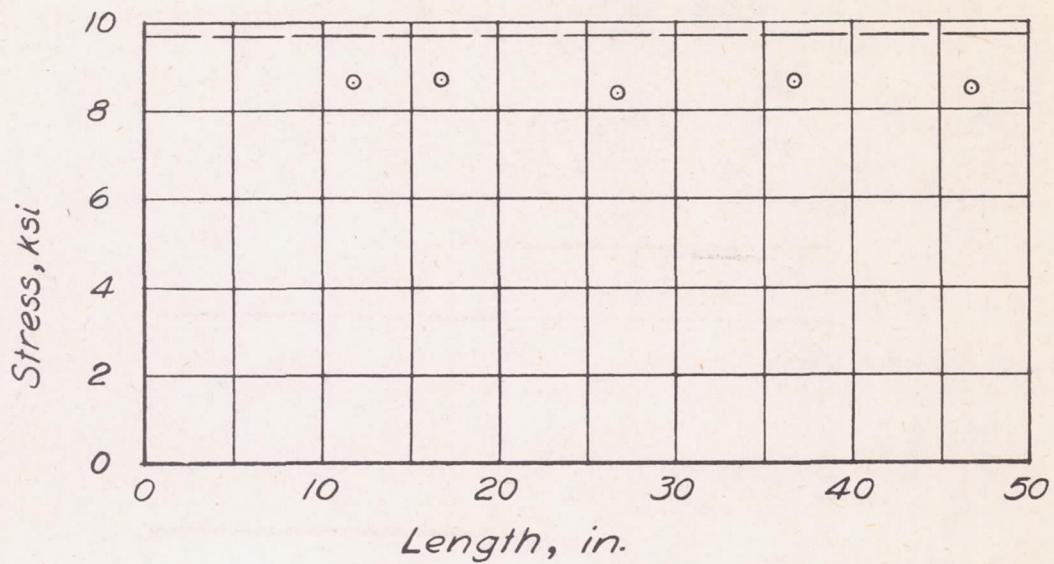
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Figure 10.-Portions of typical records obtained for two different lengths of tube.

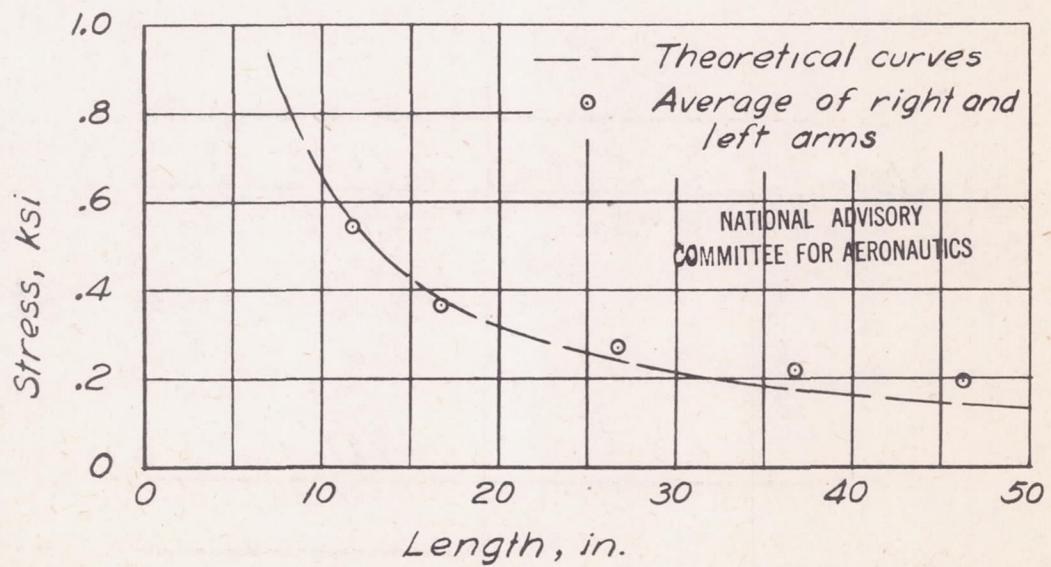


For 1-in. O.D. tube, 0.028-in.-thick wall,  
26  $\frac{3}{4}$  in. long

Figure 11.- Theoretical wave form for extreme-fiber bending stress at root obtained from the first three modes of vibration.

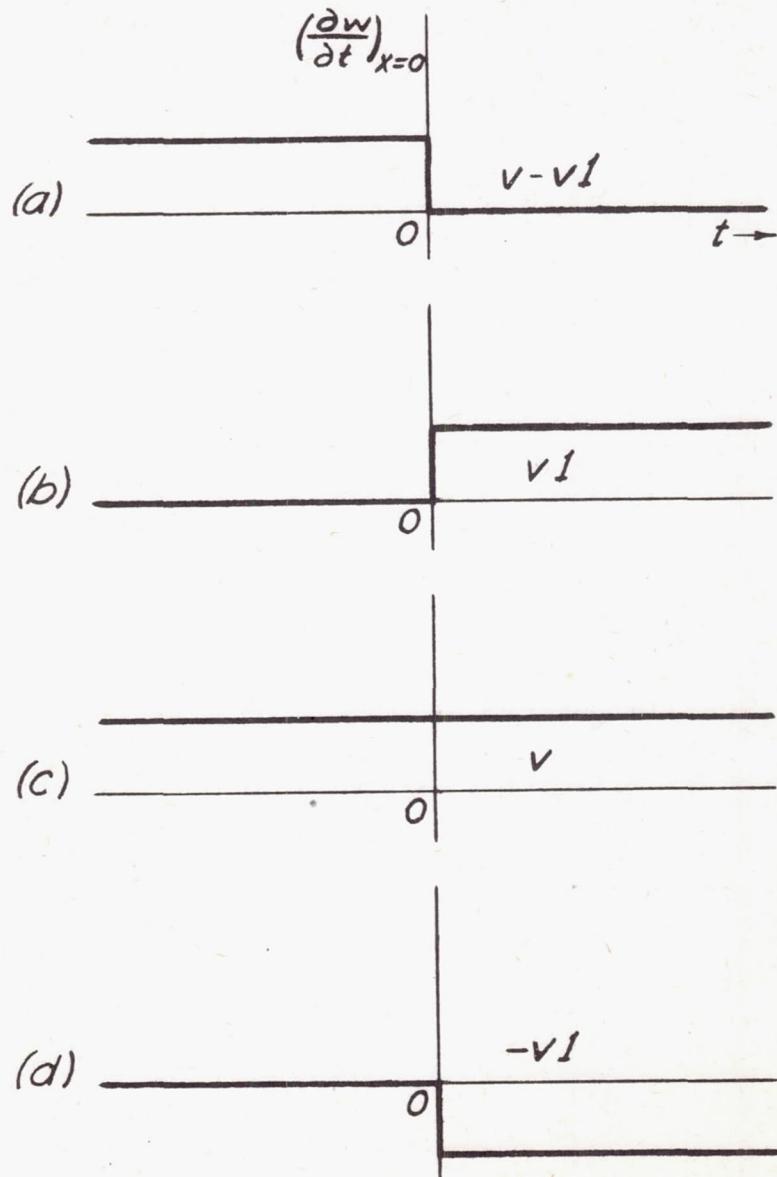


(a) Bending.



(b) Shear.

Figure 12.- Comparison of experimentally and theoretically determined maximum stresses of fundamental mode at root of cantilever tube. Impact velocity = 2.5 feet per second.



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Figure 13.- Graphic representation of various velocity functions.